

# X-LRQ075DL-E01C Datasheet



- 75, 150, 300, 450, 600 mm travel
- 100 kg load capacity
- Up to 840 mm/s speed and up to 300 N thrust
- Built-in controller; daisy-chains with other Zaber products
- Integrated, 500 CPR, motor mounted encoder provides slip/stall detection and recovery
- Inline and parallel drive configurations
- Ball screw and lead screw configurations
- Includes stainless steel dust cover
- Custom versions available

#### X-LRQ-EC Series Overview

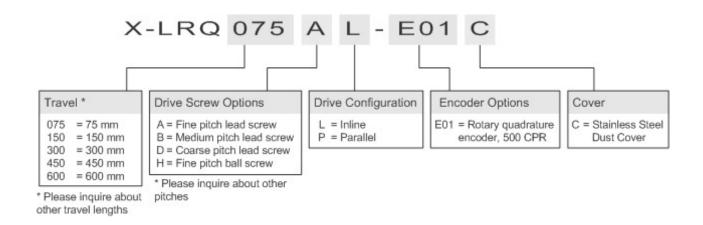
Zaber's X-LRQ-EC Series devices are computer-controlled, motorized linear stages with high stiffness, load, and lifetime capabilities in a compact size. Each device is available in either an inline or parallel drive configuration. A flexible stainless steel dust cover prevents the ingress of small objects. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

At only 48 mm high, these stages are excellent for applications where a low profile is required. The X-LRQ-EC's innovative design allows speeds up to 840 mm/s and loads up to 100 kg. Like all of Zaber's products, the X-LRQ-EC Series is designed to be 'plug and play' and very easy to set up and operate. These stages can bolt together into XY and XYZ systems. Some multi axis configurations may require additional accessories, please contact Zaber Technical Support to ensure the correct ones are selected.

For more information visit: https://www.zaber.comproducts/linear-stages/X-LRQ-EC/6

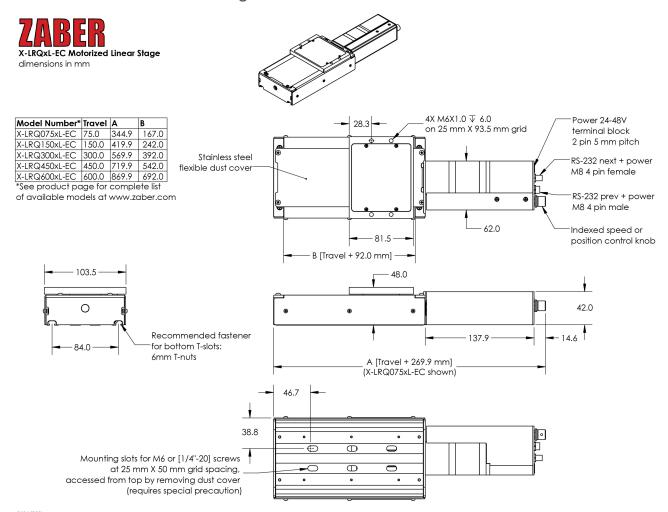
### X-LRQ-EC Series Part Numbering



X-LRQ075DL-E01C Bundle Options
This device may be purchased stand-alone or bundled with one of the following accessory kits:

Products	Description
X-LRQ075DL-E01C	Motorized, lead-screw driven, covered linear stage, 75 mm travel, integrated motor encoder and controller, coarse resolution, high speed, inline drive
with KX14C accessory kit Power supply: North America, 48 V. Powers multiple X-Series devices	<ul> <li>1 x PS14S-48V37: Power Supply, 48 V 3.75 A, Compatible with X-Series Products</li> <li>1 x X-DC06: Data Cable, 6 ft (2 m), for Use with all X-Series Products</li> <li>1 x X-USBDC: USB to Serial Converter Cable with M8 Female Plug for X-Series Products</li> </ul>
with KX13C accessory kit Power supply: North America, 48 V. Powers one axis	<ul> <li>1 x PS13S-48V12: Power Supply, 48 V 1.25 A, Compatible with X-Series Products</li> <li>1 x X-DC06: Data Cable, 6 ft (2 m), for Use with all X-Series Products</li> <li>1 x X-USBDC: USB to Serial Converter Cable with M8 Female Plug for X-Series Products</li> </ul>
with PTB2 accessory Power Supply Not Included	• 1 x PTB2: Power Terminal Block, 2 Pin, 5 mm Pitch, for Use with X-Series Devices with Custom Power Supply

#### X-LRQ075DL-E01C Drawings



# X-LRQ075DL-E01C Specifications

Specification	Value	Alternate Unit
Microstep Size (Default Resolution)	1.984375 μm	
Built-in Controller	Yes	
Travel Range	75 mm	2.953"
Accuracy (unidirectional)	108 μm	0.004252"
Repeatability	< 4 μm	< 0.000157"
Backlash	< 80 µm	< 0.003150"
Maximum Speed	840 mm/s	33.071"/s
Minimum Speed	0.001212 mm/s	0.000048"/s
Speed Resolution	0.001212 mm/s	0.000048"/s
Encoder Resolution	500 CPR	2000 states/rev
Encoder Type	Rotary quadrature encoder	
Peak Thrust	25 N	5.6 lb
Back-driving Force	27 N (± 30%)	6.1 lb (± 30%)
Maximum Continuous Thrust	25 N	5.6 lb
Maximum Continuous Illiust		
Communication Interface	RS-232	
Communication Interface	RS-232	224.3 lb
Communication Interface Communication Protocol	RS-232 Zaber ASCII (Default), Zaber Binary	
Communication Interface Communication Protocol Maximum Centered Load	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N	224.3 lb
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N 3000 N-cm	224.3 lb
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N 3000 N-cm Recirculating Ball Linear Guide	224.3 lb 4248.4 oz-in
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N 3000 N-cm Recirculating Ball Linear Guide < 20 µm	224.3 lb 4248.4 oz-in < 0.000787"
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N 3000 N-cm Recirculating Ball Linear Guide < 20 μm < 20 μm	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787"
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch	RS-232 Zaber ASCII (Default), Zaber Binary 1000 N 3000 N-cm Recirculating Ball Linear Guide < 20 µm < 20 µm 0.025°	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787" 0.436 mrad
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch Roll	RS-232  Zaber ASCII (Default), Zaber Binary  1000 N  3000 N-cm  Recirculating Ball Linear Guide  < 20 µm  < 20 µm  0.025°  0.01°	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787" 0.436 mrad 0.174 mrad
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch Roll Yaw	RS-232  Zaber ASCII (Default), Zaber Binary  1000 N  3000 N-cm  Recirculating Ball Linear Guide  < 20 µm  < 20 µm  0.025°  0.01°  0.02°	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787" 0.436 mrad 0.174 mrad 0.349 mrad
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch Roll Yaw Stiffness in Pitch	RS-232  Zaber ASCII (Default), Zaber Binary  1000 N  3000 N-cm  Recirculating Ball Linear Guide  < 20 µm  < 20 µm  0.025°  0.01°  0.02°  640 N-m/°	224.3 lb 4248.4 oz-in  < 0.000787" < 0.000787" 0.436 mrad 0.174 mrad 0.349 mrad 27 µrad/N-m
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch Roll Yaw Stiffness in Pitch Stiffness in Roll	RS-232  Zaber ASCII (Default), Zaber Binary  1000 N  3000 N-cm  Recirculating Ball Linear Guide  < 20 µm  < 20 µm  0.025°  0.01°  0.02°  640 N-m/°  1850 N-m/°	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787" 0.436 mrad 0.174 mrad 0.349 mrad 27 µrad/N-m 9 µrad/N-m
Communication Interface Communication Protocol Maximum Centered Load Maximum Cantilever Load Guide Type Vertical Runout Horizontal Runout Pitch Roll Yaw Stiffness in Pitch Stiffness in Roll Stiffness in Yaw	RS-232  Zaber ASCII (Default), Zaber Binary  1000 N  3000 N-cm  Recirculating Ball Linear Guide  < 20 μm  < 20 μm  0.025°  0.01°  0.02°  640 N-m/°  1850 N-m/°	224.3 lb 4248.4 oz-in < 0.000787" < 0.000787" 0.436 mrad 0.174 mrad 0.349 mrad 27 µrad/N-m 9 µrad/N-m

Specification	Value	Alternate Unit
Linear Motion Per Motor Rev	25.4 mm	1.000"
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	2300 mA/phase	
Inductance	2.8 mH/phase	
Default Resolution	1/64 of a step	
Data Cable Connection	Locking 4-pin M8	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic home sensor	
Manual Control	Indexed knob with push switch	
Axes of Motion	1	
LED Indicators	Yes	
Mounting Interface	M6 and M3 threaded holes	
Operating Temperature Range	0 to 50 °C	
Vacuum Compatible	No	
RoHS Compliant	Yes	
CE Compliant	Yes	
Weight	2.38 kg	5.247 lb

#### X-LRQ-EC Series Charts

